

NASA'S TECHNOLOGY INFUSION REPARE THE PROPERTY OF THE PROPERT

NEW MEXICO STATE UNIVERSITY

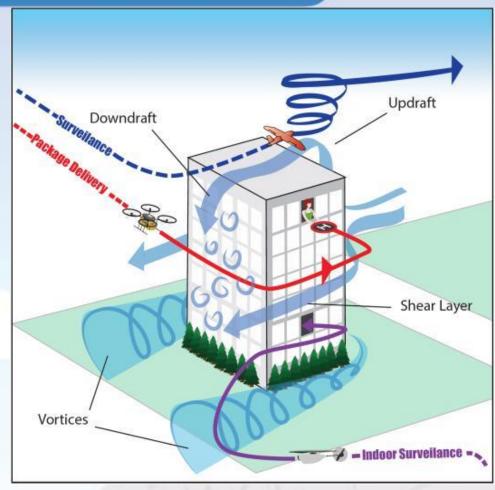
Safe Operation of Collaborative Small Unmanned Aerial Systems in Challenging Environments

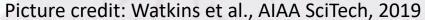
Liang Sun, MAE, NMSU August 13, 2019





Motivation: UAM Challenges







Picture credit: Electronic Design



Autonomy Framework

Data

Command

Sense

- GPS
- IMU
- Altimeter
- LiDAR
- Camera

Think

- Wind Profile Generation
- Wind Estimation
- Wind Prediction
- Path Planning

Act

Adaptive,
 Robust Flight
 Control w/
 Uncertainty

- Wind Profile Generation
 - Airwakes modeling and reduced-order model using CFD (collaborator: <u>Dr. Andreas Gross</u> @NMSU)
- Wind Visualization
 - Application of Particle Image Velocimetry (PIV) (collaborator: <u>Dr. Fangjun Shu</u> @NMSU)
- Collaborative Wind Estimation and Prediction
- Distributed Adaptive Control w/ Uncertainty

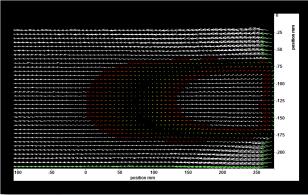
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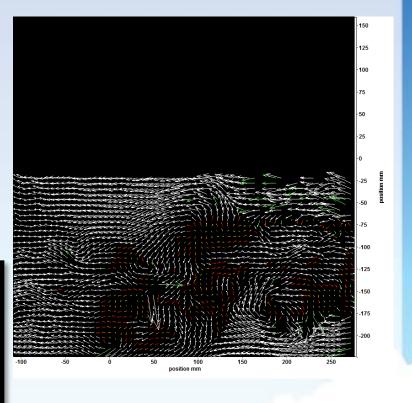
CFD Modeling and Wind Tunnel Testing

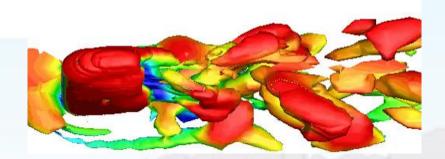








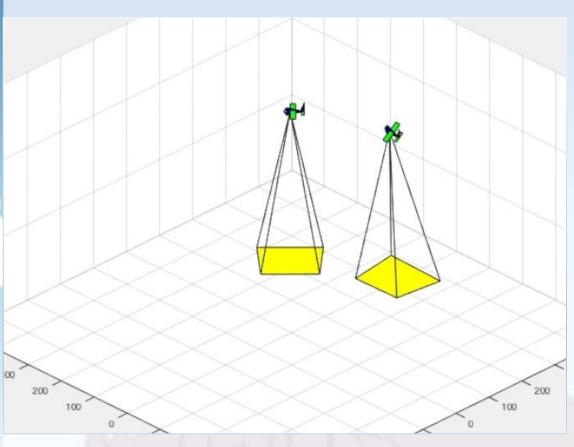


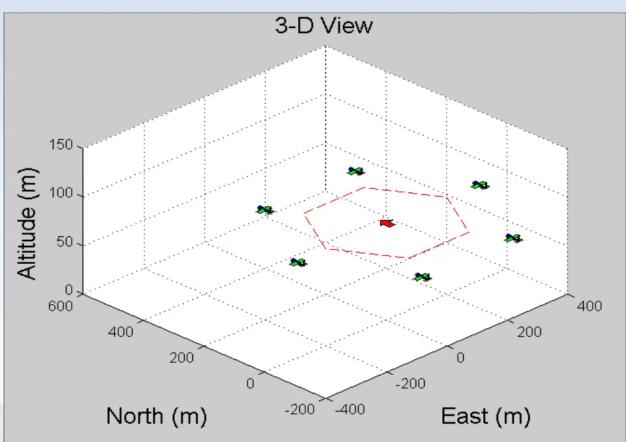




Distributed Adaptive Control

Formation Flight in GPS-Degraded Environments

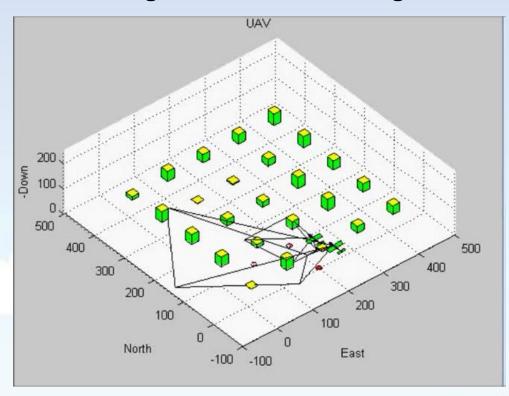






Other Projects

Multi-Target Search and Tracking



Research Topics:

- Decision-Making/Optimization w/ Uncertainty
- Distributed Dynamic Task Allocation
- Collaborative Path Planning

Autonomous Tethered Drones



Research Topics:

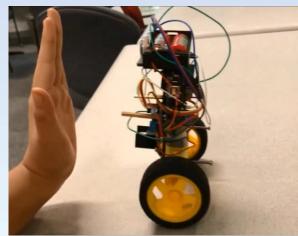
- Dynamics Modeling
- Learning-Aided State Estimation
- Distributed Adaptive Control

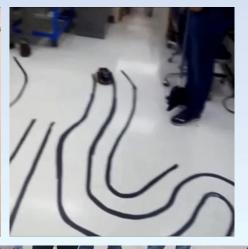


Education

Electronics and Systems Engineering (ME210)













Mechatronics (ME487/587)







